



# WowWee MiP Robot Body Disassembly

Open the chassis of your WowWee MiP robot.

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## INTRODUCTION

This guide is designed to help users disassemble the body of the WowWee MiP robot. This guide is a prerequisite for other replacement and repair guides.

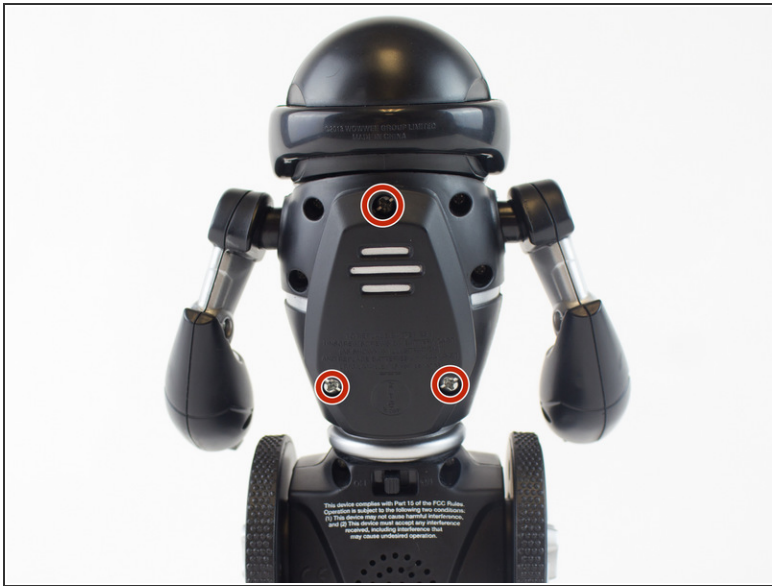
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### TOOLS:

- [64 Bit Driver Kit](#) (1)
  - [Phillips #1 Screwdriver](#) (1)
  - [Tweezers](#) (1)
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## Step 1 — Battery



- Remove the three 12.0 mm Phillips # 2 screws from the battery cover.

## Step 2



- Carefully pull the battery pack from the robot.
- Remove the batteries from the battery pack.



### Step 3 — Wheel



- Use a metal spudger to carefully pry off the hubcap without marring the plastic wheel or hubcap.

**i** This plastic material is not replaceable. Any damage will be noticeable.

### Step 4



- Remove the 12.0 mm Phillips #2 screw.

**i** Hold the wheel in place, or it will rotate as you attempt to remove the screw.

## Step 5



- Pull the wheel off of the square axle.

⚠ Do not use excessive force while removing the wheel. Pulling too hard on the wheel can damage the axle.

## Step 6 — WowWee MiP Robot Body Disassembly




- Remove the eight 9.3 mm Phillips #1 screws from the back of the robot.

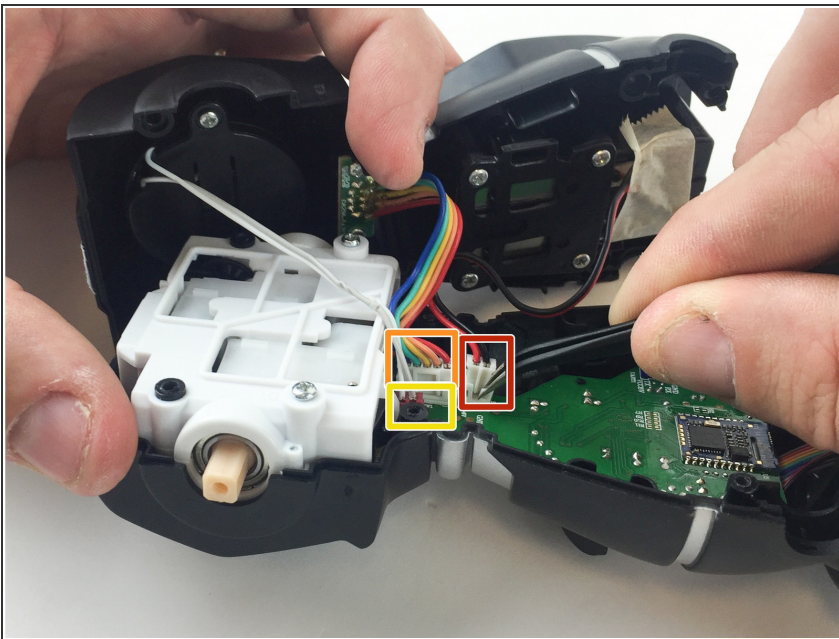
## Step 7



- Remove the arms from the body.
- Carefully open the body compartment.

 Open the compartment slowly. There are wires connecting the two body pieces together. If pulled too hard, the wires and/or the motherboard could be damaged.

## Step 8



- Using precision tweezers, disconnect the following three bundles of wires:
- Connecting the battery pack to the motherboard.
- Connecting the power switch to the motherboard.
- Connecting the speaker to the motherboard.

To reassemble your device, follow these instructions in reverse order.

